A COMPARISON OF FLUVIAL AND COASTAL SIMILITUDE

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ABSTRACT

A comparison of the conditions of similitude for movable bed scale models of rivers and estuaries on one hand, and beaches and shorelines on the other hand, is presented. It is demonstrated that despite the fact that the knowledge in sediment transport by wave action is less advanced than in the case of steady current, the conditions of similitude for beaches are less stringent than for rivers. In particular, the effect of relative roughness is comparatively unimportant in the case of beaches, while the necessity of similitude of head loss imposes an imperative condition in the case of scale models of rivers. An introduction to a natural law of distortion for beaches is presented in analogy with the Lacey condition for rivers.

INTRODUCTION

Belief in movable bed scale model technology is somewhat mystical—God’s existence can be proven by logic, while as many reasons can be proposed for proving the opposite. This belief is not a matter of logic—it is a matter of faith. Similarly, agnostic specialists in sediment transport can easily find many reasons why similitude of movable bed scale models is not possible. On the other hand, hydraulic engineers believe in movable bed scale model technology as a tool for solving practical problems and guiding their intuition. Sometimes this belief or disbelief is completely irrational. One finds the scientist who does not want to admit that this tool could be of practical value and one also finds the engineer whose faith in his scale model fringes on the rim of superstition, while he should know its limit of validity. The analogy can be further prolonged by considering that different scale model practices and technology prevailing in different hydraulic laboratories correspond to slightly different religions. But the road to salvation is not unique—despite some disagreement between laboratories on what should be done, none of these methods is “completely wrong.” One can only discuss what could be the most universal approach—the better approach actually being the one which is the best mastered by individual experimenters.

A detailed investigation of what can and cannot be done in movable bed scale models dealing with coastal structures has been presented in a previous report (Fan and Le Mehauté, 1969). This presentation will be limited to some reflections which may not necessarily be original, but which are felt pertinent to this convention, which assembles agnostics as well as believers in movable bed scale models. One would like to clearly establish that the chance for success of a movable bed scale model dealing with shoreline processes is much higher than a movable bed model of fluvial hydraulics. Subsequently, the first kind of model will require less knowledge in the law of sediment transport and less astuteness on the part of the experimenter than the second kind.

The reasons which make a coastal model more reliable than a river model are:

a) A less imperative choice of the condition of similitude. This is discussed at length in the following. In general, coastal models do not
require any condition on bottom roughness, while the necessity of reproducing head loss in similitude in fluvial models imposes an additional condition upon the size of the model material to be used.

b) A wider choice of criteria of similitude in the case of a coastal model. One can always satisfactorily reproduce an observed shoreline evolution by adjusting wave height, period, direction, duration, or intensity of tidal current. (However, similitude of sand deposit taking place in a diffraction area may be subjected to scale effects.)

In fluvial hydraulics, the choice of criteria is limited to typical flood histograms and required fineness of topography. (Secondary meandering effect may not need to be reproduced in similitude.)

c) The third reason for making coastal models more successful is related to the problem of hydraulic instability. A river flowing in its own alluvium is fundamentally unstable in the sense that if there is erosion, more water will flow, and, consequently, more erosion will follow. The study of a meandering river on a scale model is only possible if the banks are fixed. A meandering process can be reproduced on a scale model only if it obeys a well defined cycle, such as the Seine estuary.

In coastal processes, if one excepts cusps and rip currents on long, straight beaches, the flow pattern is generally well determined by an imposed bottom topography. Short coastal engineering scale models always deal with well-defined topography and man-made works, such as harbor entrances. Consequently, there is a general tendency towards a stable state. A dune tends to be flattened out and a channel tends to be filled.

d) Finally, the last reason for the success of coastal engineering models is due to the fact that beaches are generally made of relatively uniform non-cohesive material, while rivers may present a much wider size distribution of material and have cohesive characteristics. The law of similitude for cohesive material cannot be established until more is known about the sediment transport of cohesive material.

PRELIMINARY REMARKS

Prior to entering this subject, it is pertinent to briefly recall some of the fundamental principles governing movable bed scale model technology.

1) Quoting L. F. Vernon-Harcourt, who continued the work of Reynolds:

"If I succeed in demonstrating with the model that the originally existing conditions can be reproduced typically, and if, moreover, by placing regulating works in the model, the same changes can be reproduced that were brought about by the training works actually built, then I am sure that I can take the third and most important step, namely, of investigating, with every promise of success, the probable effect of the projects that have been proposed."

This principle has been the basic guideline ever since.

2) A movable bed scale model must fulfill the following conditions:

a) It must be exact; i.e., it must reproduce with exactness the natural phenomenon under study.
b) It must be consistent i.e., it must always give the same results under the same conditions.

c) It must be sensitive—or more exactly, its sensitivity has to be imposed by the fineness of the topography which needs to be reproduced for the phenomenon under investigation. Secondary meandering flow, small benches, and at the limit ripples, will, of course, not need to be reproduced in the scale model.

d) It must be economical, of reasonable size, and completed within a reasonable time interval.

3) In a movable bed scale model, the basic similitude requirement is the reproduction of bottom evolution observed in the field even if it is not achieved through exact similitude of water motion (the way in which water motion is simulated must be logical so that it can be extended to future conditions). Reproducibility of test results under the same conditions is a general requirement for all experimental studies. This requirement of the model also implies stability under random disturbances. An unstable phenomenon cannot be studied adequately in a movable bed model.

"For example, it would be illusive to study the stability of a river flowing in its own alluvium on a scale model because a simple bush or a local soil a little more cohesive can definitely guide a meander in a way different from the model result. Such studies embody by their very nature a risk of complete failure." (Le Méhauté, 1962)

4) It is important to distinguish between conditions of similitude and criteria of similitude. The conditions of similitude are an ensemble of formulas deduced from the physical laws governing the phenomena under investigation. E.g., the similitude condition governing sediment transport is obtained by an analysis of the mechanics of sediment transport. They have an absolute definition which cannot be changed unless an improvement in the knowledge of the physical law is obtained. They are not chosen by the experimenter but are imposed on him. Unfortunately, it is known that in the field of sediment transport, many phenomena still remain to be analyzed or clarified. Thus, the conditions of similitude are not as well defined as they should be. A choice of what is important will have to be based again on the knowledge of these laws obtained by "inspectional analysis".

In performing a model study, an experimenter must specify certain criteria such as model wave conditions and fineness of model bottom features. The criteria of similitude is a free choice of the experimenter to a very large extent. For example, sea states vary from day to day and from hour to hour. The experimenter will choose, for the sake of simplicity as well as practical necessity, a characteristic wave condition and will only be able to reproduce simplified storm and swell conditions on the scale model. He will choose the wave direction and the wave amplitude and the duration guided by his knowledge of natural conditions. In particular, the wave generator will generate waves at an angle which corresponds to the dominant direction of storm wave energy. Even though he is guided by his knowledge of wave statistics, his final choice will be determined by a trial and error method which permits him to reproduce the same bottom evolution as observed in the prototype. This faithful reproduction of bottom evolution determines
the choice of the wave characteristics, rather than the strict conditions of similitude of wave motion

Other criteria of similitude will be to what extent he wants to reproduce the fineness of the bottom topography, a typical tide cycle, the currents and their variations with time, and so on. In summary, the criteria of similitude are specified by the experimenter as reasonable approximations for simplification of model operation.

5) Movable bed scale models are distorted, i.e., the vertical scale is different from the horizontal scale. Distortion is not an engineering trick for reducing the size of the model and the bottom friction, but is the extrapolation of a natural observed phenomenon. The method to obtain a satisfactory scale model is first to obey the law of nature, even though this law may not be fully understood. For example, a small river flowing in its own alluvium can be considered a distorted model of a large river. This means that the ratio depth to width of the small river is comparatively greater than the relative depth of the larger one. The ratios of depths \( \lambda \) and widths \( \mu \) are approximately related by the law of Lacey \( (\lambda^2 = \mu^3) \), in accordance with the "regime theory." Similarly, a beach in a protected area has a relatively steep slope, while a beach in an exposed area tends to have a more gentle slope (Wiegel, 1964). The vertical scale being defined by the ratio of incident wave heights, a protected beach can be considered as a distorted scale model of an exposed beach. In both the case of the river and the beach, the choice of distortion becomes a stringent condition to be respected quantitatively, however, the natural law determined by statistical observation of natural phenomena needs to be modified in the case of a river model due to the fact that scale models generally do not use the same material as the prototypes in order to satisfy other conditions of similitude. On the other hand, natural distortion based on the use of sand is compatible with other conditions of similitude in the cases of beaches as will be seen in the following. However, the use of sand would rather be discarded as leading too large a distortion and, subsequently, to large scale effects.

6) To the old teaching tradition which consists of presenting a parallel between Froude and Reynolds similitude, I would prefer to make a parallel between what we can call "short model" and "long model." In a short scale model, viscous friction is unimportant as compared to gravity and inertia, therefore, it is governed by Froude similitude. Also, energy dissipation may result from a fully turbulent condition, as in the case of a hydraulic jump or a wave breaking on a beach. Boundary layer effects in both cases are unimportant. The dissipative forces are also proportional to the square of velocity like the inertial forces. (A small hydraulic jump is a scale model of a large hydraulic jump under proper depths-discharge relationships.) This is the generalized Froude similitude.

On the other hand, in a long model, friction has a definite influence on the flow pattern; therefore, in addition, a similitude of head loss is required. This head loss is a function of the Reynolds number, but is not determined by the so-called Reynolds similitude requiring an equality of Reynolds numbers. Therefore, similitude for long models requires, in addition to the Froude similitude, another condition which makes long models more difficult, if not impossible, to handle. The model of a smooth concrete-lined gallery cannot provide a "Froudian" discharge under similar pressure head, since the friction coefficient can only be larger at a smaller Reynolds number (Moody diagram). On the other hand, the head loss in the scale model of a rough (rocky) gallery can be adjusted for the same friction factor insuring the Froude similitude to be satisfied.
The magnitude of long shore currents and location of rip currents may, to some extent, depend upon friction characteristics of the beaches, in which case the study of this phenomena would have to be considered as belonging to the categories of long models, and therefore, may not be studied on scale models. Nevertheless, most scale model studies have to deal with short coastal structures (like entrance of harbor), and therefore, the water motion is not too dependent upon the friction coefficients. The main dissipative mechanism is due to wave breaking. If viscous damping is too significant, as in the case where the wave has to travel a long distance in very shallow water, it just means that the model is not properly designed. However, very rarely do we have to be concerned with adjustments of roughness for similitude of energy dissipation, and coastal models can be considered as short models. On the other hand, as has been pointed out previously, a similitude of head loss is imperative for models of rivers and estuaries--these are long models. Despite this adjustment, vertical velocity distribution being a function of the Reynolds number could never be in similitude.

This relative advantage of a short model is somewhat balanced by the lack of knowledge of sediment transport by wave action. The law of sediment transport in rivers is relatively well understood. Therefore, the condition of similitude may be established with more certainty than in the case of beaches. Boundary layer characteristics do not vary too much from one place to another. While on the other hand, in the case of beaches, the boundary layer characteristics vary from offshore to the upsurge of the wave. A choice has to be made concerning which part of the beach we want to have the best similitude requirements. In general, it will be in the breaking zone, where the shearing force at the bottom is quadratic. However, it is to be realized that because of this variation of boundary layer characteristics from place to place perpendicular to the beach, a total similitude is impossible.

In designing a movable bed model, there are four basic unknowns, namely, horizontal scale $\lambda$, vertical scale $\mu$, sediment size $\delta$, and sediment specific weight $\gamma_s$, which require at the most four basic equations. However, the horizontal scale is generally determined by economic considerations and available space. The three remaining unknowns are relatively well determined in the case of a river, by a well accepted unique set of conditions of similitude as summarized in the following section.

In the case of beaches, there is a great controversy concerning which condition of similitude should be imperative. This controversy is due on one hand to a lack of knowledge of the law of littoral processes, but is also due to the fact that the road to a successful coastal model is not unique. As a matter of fact, a thorough analysis of the subject matter may only lead to two conditions which give us a free choice for one of the unknowns. These conditions are: 1) an equality of ratio of shearing force to relative gravity, the shearing force being quadratic as in the case of a turbulent boundary layer, and 2) a second condition is imposed by the law of distortion of beaches (equilibrium profile of beaches) under different wave actions, which embodies globally many misunderstood phenomena. In addition to these two, one can choose somewhat arbitrarily another condition, such as a dynamic condition $u/\gamma = \lambda/\mu$, where $u$ is a horizontal current, $\omega$ is the free fall velocity of the particles. One would rather choose an equality of boundary layer Reynolds number $Re_b$. The theoretical formulation based on these assumptions is presented in the following section, based on the assumption that the scale for the friction factor is the same as in the case of a fully turbulent flow, as in the surf zone.
This relative freedom is partly due to the lack of understanding of the law of sediment transport under wave action. But it is also an indication of one of the reasons why coastal models are generally more successful than fluvial models.

9) It is pertinent to point out that since the only requirement of a movable bed model is a reproduction of bottom evolution, it is not necessary that this be achieved through exact similitude of water motion. Since the model is distorted, a similitude wave refraction and wave breaking only is being searched as a most satisfying condition, susceptible to producing satisfactory reproduction of long shore current and sediment transport distribution. This is achieved by keeping the ratio of wave lengths and wave heights like vertical scale. Based upon this condition, the following wave characteristics are preserved in the model: a) wave steepness, b) refraction pattern and angle or refraction with bottom contours, c) breaking angle of wave crests with shorelines if the distortion is not too large, and d) breaking depth.

Also, the scale for long shore current and mass transport velocities is approximately \( \mu \frac{U}{L} \). Therefore, the ratio of scales of wave particle velocity to current velocity is approximately unity.

A BRIEF REVIEW OF THE HYDRAULIC PROPERTIES OF SEDIMENTS UNDER WAVE ACTION AND CURRENT

1) It is first recalled that in the case of water waves, the laminar shear velocity \( u \) (see Appendix for notation)

\[
\tau = \sigma = U_0 \frac{1}{\sqrt{\pi T}} \frac{1}{\sinh kd}
\]

For \( R > 160 \), the boundary layer flow is turbulent, then the turbulent bottom shear

\[
\tau = f \sqrt{g D} \left( \frac{w}{gD} \right) \]

In Stokes range, \( wD/\nu \),

\[
\frac{w}{\sqrt{gD}} = \frac{1}{18} \left( \frac{gD}{\nu} \right)
\]

3) In coastal processes, the sediment motion is caused by wave and tidal current actions. In studying such interactions, an important criterion is the critical condition, initiation of sediment motion. Shields' criterion of the initiation of sediment motion is in the case of a steady current

\[
\frac{\tau}{wD} = f \left( \frac{1}{\nu^2} \right)
\]

where \( \tau \) is the critical shear stress, \( \nu \) is the critical boundary layer Reynolds number based upon grain diameter \( D \).
If a boundary layer densimetric Froude number $F_\alpha$ is defined as $F_\alpha = \frac{u_\kappa}{\sqrt{g\gamma D}}$ (7), then Equation (6) can be expressed as $F_\alpha = f \left( \frac{R_*}{C} \right)$ (8), where $F_{\alpha C}$ is the critical boundary layer Froude number. For a given size of sediment, a critical velocity $u_C$ can easily be derived by noting the relation $u = C \frac{u}{\sqrt{g}}$, where $C$ is the Chezy coefficient (9).

Such criterion has also been investigated extensively in the case of sediments under wave action. It is remarkable that the criterion is identical with that of the steady current case, although the range of $R_\alpha$ is considerably smaller. For initiation of sediment motion due to wave action, the boundary layer Reynolds number $R_*^\infty$ based on grain diameter is given by

$$R_*^\infty = 2 \frac{1}{D} \left( \frac{H^2}{v T^2 \sinh k_d} \right)^{1/4}$$ (10)

At present (1970), there is no experimental information on initiation of sediment motion due to combined wave and current actions known to the authors. Based upon dimensional consideration of similar nature as Equation (8), the criterion can be expressed as

$$F_{\alpha C} = f \left( \frac{u_{w,0}}{u_{w,0}^C}, \frac{u_{w,0}}{u_{\alpha C}} \right)$$ (11)

where $F_{\alpha C}$ and $R_*^\infty$ are critical boundary layer Froude and Reynolds numbers, based upon either wave or current shear velocities $u_w$ or $u_{\alpha C}$ respectively. The parameter $u_{w,0}/u_{\alpha C}$ shear velocity ratio represents the relative importance of wave and current effects. An additional factor is the angle of wave incidence to the current direction $	heta$.

The volume transport rate of bed load $q_s$ can be expressed in general as a function of boundary layer Reynolds number, $R_*^\infty$, boundary layer Froude number $F_\alpha$ and sediment size distribution

$$\frac{q_s}{u_\kappa} \frac{1}{D} = f_1 \left( R_*^\infty, F_\alpha, \sigma_D \right)$$ or

$$\frac{q_s}{u_\kappa} \left( \frac{u_\kappa^2}{g} \right)^{1/2} = f_2 \left( R_*^\infty, F_\alpha, \sigma_D \right)$$ (13)

where $q_s$ is the volume sediment transport rate per unit width. The effect of distribution of the sediment size is considered by including the geometric standard deviation $\sigma_D$.

Sediment transport by waves is mainly due to mass transport and longshore currents. On a beach, the onshore and offshore transport of sediments are reflected by the beach profiles. The alongshore transport of sediment (i.e., littoral drift) is induced by longshore currents. For bed load transport due to combined wave and current action, the volume rate is expected to be affected by two additional parameters,

$$\frac{q_s}{u_\kappa} \frac{1}{D} = f_1 \left( R_*^\infty, F_\alpha, \sigma_D \right)$$ or

$$\frac{q_s}{u_\kappa} \left( \frac{u_\kappa^2}{g} \right)^{1/2} = f_2 \left( R_*^\infty, F_\alpha, \sigma_D \right)$$ (13)

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namely, 1) the ratio of characteristic velocities between current and wave $u_c/u_w$, and 2) the incident angle of wave to the current direction $\theta$

$$\frac{q_g}{u_\perp (u_\perp / g)} = f(R_\perp, F_\perp, u_c/u_w, \theta, \sigma_D)$$  \hspace{1cm} (14)

5) Beaches are formed by wave and coastal sediment interactions. Beaches are said to be in equilibrium when they reach stable profiles under relatively constant wave action. This means that the offshore and onshore transport of sediments are in balance. In general, the form of equilibrium profile of a beach depends upon the wave characteristics, such as wave height and wave length or wave steepness, sediment specific weight and sizes.

There is no well-established law on beach equilibrium which can be applied both to offshore and surf zones, or to both natural sand and scale model light material. A study is now being conducted at Tetra Tech for this purpose.

6) The most commonly accepted relation for littoral drift is approximately

$$\frac{\gamma_f E}{2g (\gamma_s - \gamma_f) D} = K Q_s \left(\frac{\gamma_s - \gamma_f}{\gamma_f}\right)^{1/2} \left(\frac{1}{g D^3}\right)^{1/2}$$  \hspace{1cm} (15)

where $E$ is the longshore energy and $K$ a constant coefficient (Manohar, 1962).

SIMILITUDE RELATIONS FOR MOVABLE BED RIVER MODELS

The similitude relations for movable bed river models are derived based upon similitudes on (Boucher and Le Mehaute, 1957) 1) basic flow characteristics and flow patterns, 2) head loss, 3) sediment transport characteristics and 4) kinematic condition on sediment motion.

As in a coastal model, there are four basic scale ratios to be determined: namely, $\lambda$, the horizontal scale; $\mu$, the vertical scale (or distortion, $\alpha$); $D$, artificial sediment size; $\gamma'$ apparent specific weight. However, in many river model studies, an extra distortion is allowed for the river slope. Here, only the case with one distortion is discussed.

For similitude on basic flow characteristics and flow patterns, the model flow conditions are deduced based upon the Froudiaw law. The scale ratio of flow velocity $n_u$ is $n_u = u_c^2$ and the time scale $n_t$ is $n_t = \lambda u_c^{1/2}$  \hspace{1cm} (16)

For similitude of head loss, there are two conditions: 1) the energy gradient, and 2) the bed configuration. Based upon Chezy's formula

$$u = C_c \sqrt{dS/e}$$

where $C_c$ is the Chezy coefficient and $d$ is the water depth. $R_h$ is the hydraulic radius for wide rivers. $S_e$ is the energy gradient.

Since the energy gradient for a distorted model must be exaggerated by a factor of $\Omega$, the scale ratio for the Chezy coefficient $n_{C_c}$ is $n_{C_c} = \Omega^{-1/4}$  \hspace{1cm} (18)

and $n_f = \Omega$. 
This condition is valid for movable bed models as well as for fixed bed models (For the latter, the head loss is set up experimentally without taking into account the relative roughness.) For movable bed models, since the flow is kept fully turbulent, \( C_c \) can be expressed as:

\[
C_c = K \left( \frac{d}{D} \right)^{1/6}
\]

(19)

where \( K \) is a proportionality constant, and \( D \) is the sediment size.

A necessary condition for this Equation for \( C_c \) to be applicable is that there should be no ripples or dune formation in the model. This condition is:

\[
R* = \frac{u^*}{\nu} = 11 \cdot 6 \cdot \frac{D}{\delta} > 500 \text{ (in the model), where } R* \text{ is a boundary layer Reynolds number, } u_* = \sqrt{\frac{g d S_e}{\epsilon}} \text{ is the shear velocity. The condition } R* > 500 \text{ implies } R > 500 \text{ where } R = \frac{u_* H}{\nu} \text{ (i.e., the flow is fully turbulent in the model)}
\]

Then the scale ratio for the sediment size \( n_D \) is given by:

\[
n_D = \mu n^3
\]

(22)

For the similitudes of sediment transport characteristics, there are three basic aspects namely, 1) initiation of sediment motion, 2) regimes of bed configuration and 3) bed load sediment transport characteristics. So far, modeling of the suspension transport has not been carried out.

The condition of initiation of sediment motion due to current action, as discussed in a previous section, is:

\[
F'_{C} = f \left( R_{*C} \right), \quad \text{where } F'_{C} \text{ is the critical boundary layer Froude number, and } R_{*C} \text{ is the critical boundary layer Reynolds number.}
\]

Based upon the general formula for bed load transport rate per unit width, \( q_s \) can also be expressed in general functional relationship as:

\[
q_s = \frac{u^*}{\left( \frac{u^*}{\nu} \right)^2} = f \left( R_{*}, F'_{C}, \sigma_D \right)
\]

(24)

Based upon the above reasoning, the similitudes of sediment transports including condition of initiation of sediment motion, require:

\[
n_{R*} = 1 \quad \text{and} \quad n_{\sigma_D} = 1
\]

(25, 27)

These Equations are entirely similar to those derived for coastal models. They imply:

\[
n^{2}_{u_*} n_{*}^{-1} n_{D}^{-1} = 1 \quad \text{and} \quad n_{u_*} = n_{*} \left( n_{D} \right)^{\frac{1}{2}} = \mu \left( \frac{H}{\lambda} \right)^{\frac{1}{2}}
\]

(28)

or

\[
n_{*} n_{D} = \mu n
\]

(29)

In general, \( R* \) in the field is large. For large \( R* \), the sediment transport characteristics are approximately independent of \( R* \). On the other hand, it is desirable to prevent occurrence of ripples in the model. Thus, Equation \( n_{R*} = 1 \) is relaxed in practice except specifying \( R* > 500 \) in the model. At large \( R* \), the sediment transport characteristics are believed to be dependent primarily on \( F'_{C} \). On the model bed, it is undesirable to have extensive ripple formations because the model ripples often contribute too much flow resistance in comparison with the prototype condition and their effect is difficult to control.

A kinematic condition of sediment motion is specified here as an additional basic similitude relation, a sediment in suspension travels distances in the...
vertical and the horizontal directions proportional to its fall velocity \( w \) and its horizontal velocity \( u \), \( \text{i.e} \ x/y = u/w \), where \( x \) and \( y \) are horizontal and vertical distances of travel. This Equation gives an additional condition on the basic unknowns \( \Omega = n_w/n_u = n_wu^{-\frac{1}{2}} \).

Considering the value of the fall velocity \( w \), the scale ratio \( n_w \) is then given by \( n_w = (n_{y/y}n_D/n_{fw})^{\frac{1}{2}} \), where \( n_{fw} \) is the scale ratio of the function \( f_w (wD/v) \). This condition cannot be expressed explicitly, because of the inclusion of \( n_{fw} \). However, it is interesting to note that if one uses the same sediment in the model as in the prototype, \( n_w = 1 \), the above Equation reduces to \( \lambda^2 = \mu^3 \), which matches the Lacey relation (33) based on river statistics, but \( n_{F_A} = 1 \) and \( n_{R_e} = 1 \) are then not verified.

In summary, the similitude relationships of movable bed river scale models are determined from three conditions: 1) similarity of head loss \( n_{F_A} = \Omega \), 2) similarity of sediment transport characteristics \( n_{F_A} = 1 \), and 3) kinematic condition of sediment motion \( \frac{n_u}{\mu} = 1 \) leading to a well-defined distortion. In addition, there should be no ripple formation in the model \( R_e > 500 \).

The bed load transport formula, Equation (24) is used to obtain the time scale of bed evolution \( n_{tb} \), \( n_{tb} = \lambda \mu/n_{qs} = \lambda^{\frac{5}{2}}/\mu^{\frac{1}{2}} \).

The kinematic conditions imply Lacey’s law at \( n_w = 1 \) The Lacey’s law is also compatible with the regime theory of rivers based upon statistical analyses of meandering rivers width \( \propto Q_{1/2} \), depth \( \propto Q^{1/3} \). In scale relations, it gives identical relations as the one obtained by previous considerations, \( \text{i.e} \), \( \lambda^2 = \mu^3 \).

which is often used as a guide in choosing \( \lambda \) and \( \mu \) values. However, since this is derived by assuming identical model and prototype sediments, another relationship should be used in actual choice of scale ratios. This relationship can easily be verified quantitatively from the previous set of Equations where the particle fall velocity for the light scale model material is taken into account exactly.

**SIMILITUDE OF SEDIMENT MOTION FOR COASTAL MODELS**

Similitude of sediment motion means homogeneous scaling of sediment transport characteristics in the model, \( \text{i.e} \), consistent quantitative relationships between the model and prototype transport quantities. For a distorted Froudeian model, similitude of wave refraction insures...
approximately identical \( \frac{u_c}{u_w} \) and \( \lambda \) values as in the prototype. For constant \( q_s/u_w \), it requires

\[
\frac{u_c^2}{g} = \frac{u_s^2}{g} \quad (36) \quad \frac{\mu}{\mu_s} = 1 \quad (37) \quad \text{and} \quad \frac{\sigma_D}{\sigma_s} = 1 \quad (38)
\]

(The condition \( \sigma_D \approx 1 \) is disregarded by most investigators.) These equations give

\[
n_u = n_v, \quad n_D = 1
\]

The scale for \( n_u \) is actually difficult to define, since the boundary layer characteristics vary from offshore (viscous case or ripples) to the breaking zone, where it is fully turbulent, without ripples.

In the first case (viscous)

\[
n_u = \frac{1}{8} \mu
\]

In the breaking zone

\[
n_u = \frac{1}{2} \mu
\]

Considering the state of the art, it is difficult to assess the value of \( n_f \). If one assumes that \( f \) in the surf zone is a function of the relative roughness, as in the case of a river, then \( n_f = \frac{1}{\lambda} \). Then

\[
n_u = \frac{1}{\lambda} \mu \quad (39)
\]

The use of natural sand, \( n_v = 1 \), would require that \( n_D = 1 \). This implies that model sand should be identical to the prototype sand. In this case, Equation (40) gives

\[
\lambda^2 = \mu
\]

which could be considered as the natural distortion law equivalent to Lacey condition \( \lambda^2 = \mu^3 \) for rivers. Since the scale for the slope is equal to distortion

\[
n_s = \frac{u}{\lambda}, \quad n_s = \frac{1}{\lambda} \quad (A \text{ natural beach subjected to 10 foot, 12 second waves of } \lambda \text{ will have a } \frac{1}{100} \text{ scale model slope of } 1/5 \text{ when subjected to a 1 foot, 4 second wave).}
\]

However, a lighter material than sand will actually ensure less distortion and a more gentle scale model slope, therefore, less scale effects. It is interesting to note that Equation \( \lambda^2 = \mu \) is compatible with \( n_u = 1 \) and also \( n_f = 1 \). Consequently, sand can be theoretically used on scale models of beaches.

Although similitude of \( R_\alpha \) and \( F_\alpha \) are obtained based upon the bed load transport formula, the similitude relationships have the following additional implications: 1) similitude of initiation of sediment motion, and 2) similitude of regimes of sediment motion.

Thus, such similitude relationships imply a similar and homogeneous transport characteristic over the model as in the prototype. However, there are several restrictions before the above equations for \( n_D \) and \( n_v \) can be used. These limitations are

1) Both the prototype and the model boundary layers are turbulent (this is certainly true in the surf zone).

2) The model friction factor is scaled according to distortion of \( n_f = \frac{1}{\lambda} \).

3) Size distributions of the sediments should be identical between model and prototype.
Moreover, the analysis here does not apply in the case of a pebble beach. In such a case, the condition of $n_{R_{\infty}} = 1$ is replaced by a limiting value of $R_{s}$, say, of 500.

Theoretically, relationships between scales, distortion, artificial sediments, etc., are obtained based upon similitude of sediment transport characteristics and equilibrium beach profiles. Because of the uncertainties involved, certain preliminary wave tank experiments are necessary. The purpose of such wave tank experiments is to confirm the choice of distortion and artificial sediments. The similitude of sediment transport characteristics by selecting $n_{R_{\infty}} = 1$ and $n_{F_{\infty}} = 1$ gives not only the correct scaling of bed load transport, but also the critical condition of sediment motion.

The condition $n_{R_{\infty}} = 1$ may then be too stringent and be replaced by a condition such as $R_{s} > R_{\sigma}$, where $R_{\sigma}$ is a minimum critical value for the scale model (say 160 implying a turbulent boundary layer).

An important scale ratio is the time scale of bottom evolution $n_{tb}$. The value of $n_{tb}$ is usually determined in the process of reproduction of bottom evolution. Analytically, $n_{tb}$ can be obtained from any sediment transport formula (15). For a coastal movable bed model, the littoral transport formula, is proposed here to be used for determining the value of $n_{tb}$.

$$n_{tb} = \frac{\lambda^2 \mu}{n_{Q_s} n_{D}^{1/3} n_{y^{1/2}}}$$

The littoral transport rate. This equation is applicable only in the case of coastal problems where the littoral transport is the dominant sediment transport mechanism. For river models, a different formula has already been proposed. This formula is useful in predicting time scale of bed evolution in the model. At present, there are, to our knowledge, two sets of data available for comparison.

1) Cobourg Harbor Study (Le Méhaute and Collins, 1961)

Model conditions: $\lambda = 1/200$, $\mu = 1/60$. Artificial sediment Gilsonite, $n_{y'} = 0.0182$, $n_{D} = 7$.

Time scale by model reproduction of bottom evolution $n_{tb} = 25$ min. 1 yr

Time scale from proposed Equation $n_{tb} = 117$ minutes 1 year.

In this study, the model wave height was exaggerated, approximately, by a factor of two. A correction of the wave height scaling based upon the littoral drift equation gives $n_{tb} = 29$ minutes 1 year, which is close to the predicted value.

2) Absecon Inlet Study (U.S. Waterways Experiment Station, 1943)

Model conditions: $\lambda = 1/500$, $\mu = 1/100$. Artificial sediment Sand, $n_{y'} = 1$, $n_{D} = 0.63$.

Time scale by model reproduction of bottom evolution $n_{tb} = 13$ hrs 1 yr

Time scale from proposed Equation $n_{tb} = 56$ hours 1 year.

Again there is a correction on the exaggeration of the model wave heights (a factor of about two) $n_{tb} = 14$ hours 1 year.
An additional correction is to be made due to the fact that 22 percent of time was not reproduced in the model when there was no littoral transport in the field. $n_{tb} = 11$ hours per year.

Thus, these predicted time scales compared favorably with observed values. The accuracy is estimated to be within 30 percent.

**CONCLUSION**

The success of a movable bed scale model depends upon the proper choice of distortion and material. Distortion is a natural observed phenomena, which needs to be strictly adhered to for similitude. Its choice can theoretically be justified in the case of a river, based on well defined conditions of similitude. These conditions lead to a Lacey type relationship close to $\lambda^2 = \mu^3$. The law $\lambda^2 = \mu^3$ prevails in the case where the same material (sand) is used in both the prototype and the model. This is the law of "natural distortion" which is not compatible with other conditions of similitude ($n_p = 1, n_t = \Omega$).

The choice of scales and material is less well defined in the case of beaches. However, for a given material and vertical scale, there is also a well defined rate of distortion based on the equilibrium profile of beaches. This approach compensates to a large extent for the lack of understanding of the law of sediment transport by wave action. If one assumes that the regime in the boundary layer is turbulent, the friction coefficient can be related to relative roughness (as in the case of a steady flow) and the same material, a law of "natural distortion" is also obtained such as $\lambda^{1/2} = \mu$. The first law is approximately verified by compilation of river statistics, while the second law ($\lambda^{1/2} = \mu$) is obtained from theoretical considerations. This law still needs to be proven, improved, or disproven from observation. For the time being, one can only insure that it gives a qualitatively observed trend (Wiegel, 1964). Lighter scale model material will insure a smaller rate of distortion. Therefore, the use of sand in movable scale models may provide too large a scale effect, even though it is now compatible with $n_p = 1$ and $n_r = 1$. It is hoped that present studies on equilibrium profiles of beaches will solve some of the uncertainties that have been brought out in this paper. In the meantime, preliminary 2D tests are still necessary for determining distortion prior to designing any large 3D model.

It is also hoped that the present paper will help to demonstrate that movable bed scale model technology is not "magic witchcraft" after all.

**ACKNOWLEDGMENTS**

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### Summary

**Conditions of Similitude**

<table>
<thead>
<tr>
<th>Coastal</th>
<th>Fluvial</th>
</tr>
</thead>
</table>
| **1)** Similitude of wave refraction  
  Time scale \( n_t = \frac{1}{2} \)  
  Velocity, current \( n_u = \frac{1}{3} \)  
  Similarity of wave breaking \( n_{H_b} = \frac{1}{2} \) | **1)** Normal Froude similitude for distorted model  
  Time scale \( n_t = \frac{1}{2} \)  
  Velocity \( n_u = \frac{1}{3} \)  
  \( n_{F_*} = 1 \) \( n_D \) (imperative) |
| **2)** \( n_{F_*} = 1 \) \( n_{u_*} = n_{y*} \) \( n_D \) (imperative) | **2)** \( n_{F_*} = 1 \) \( n_{u_*} = n_{y*} \) \( n_D \) (imperative) |
| **3)** \( n_{R_*} = 1 \) (not imperative, but recommended) | **3)** \( R_y > 500 \) no ripple (imperative) |
| **4)** Short model independent of relative roughness  
  \( n_{u_*} = \frac{1}{2} \) if \( n_{f_*} = \frac{1}{2} \) (surf zone) | **4)** Long model similitude of head loss, function of relative roughness  
  \( n_{C_*} = K \left( \frac{d}{D} \right)^{1/6} \)  
  \( n_{f_*} = \frac{1}{2} \) (imperative)  
  \( n_{u_*} = \frac{1}{3} \) (turbulent boundary layer) |
| **5)** Suspension  
  \( n_u = \frac{1}{2} \) \( n_{u_w} \) (not imperative) | **5)** Suspension  
  \( n_u = \frac{1}{2} \) \( n_{u_w} \) |
| **6)** Distortion imposed by equilibrium profiles of beaches (Still undetermined for light model material) | **6)** 2, 4, & 5 combined lead to a distortion with different material (imperative) |
| Natural distortion (same material), and where \( n_{f_*} = \frac{1}{2} \) \( \frac{1}{2} = \frac{1}{2} \)  
  Compatible with \( n_{F_*} = 1 \) \( n_{R_*} = 1 \)  
  but too large distortion (scale effects) | Natural distortion (same material)  
  \( \frac{1}{2} = \frac{1}{2} \)  
  Compatible with "regime theory" but not with \( n_{F_*} = 1 \) |
### Phenomena and Important Quantities

<table>
<thead>
<tr>
<th>Similitude Relations</th>
<th>Fluvial</th>
<th>Coastal</th>
</tr>
</thead>
<tbody>
<tr>
<td>A) Geometry</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Horizontal length</td>
<td>$\lambda$</td>
<td>$\lambda$</td>
</tr>
<tr>
<td>Vertical length</td>
<td>$\mu$</td>
<td>$\mu$</td>
</tr>
<tr>
<td>Distortion $\Omega$</td>
<td>$\mu/\lambda$</td>
<td>$\mu/\lambda$</td>
</tr>
<tr>
<td>Slope (river, beaches) $S$</td>
<td>$\mu/\lambda$</td>
<td>$\mu/\lambda$</td>
</tr>
<tr>
<td>B) Water Motion Characteristics</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Water depth $d$, wave breaking depth $d_b$</td>
<td>$\mu$</td>
<td>$\mu$</td>
</tr>
<tr>
<td>Wave height $H$, breaking wave hgt $H_b$</td>
<td>$\mu$</td>
<td>$\mu$</td>
</tr>
<tr>
<td>Wave length $L$</td>
<td>$\mu$</td>
<td>$\mu$</td>
</tr>
<tr>
<td>Wave period $T$</td>
<td>$\mu$</td>
<td>$\mu$</td>
</tr>
<tr>
<td>Refraction angle &amp; wave breaking angle</td>
<td>Not in similitude</td>
<td></td>
</tr>
<tr>
<td>Wave diffraction, reflection</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Time scale $t$</td>
<td>$\lambda^{1/2}$</td>
<td>$\mu^{1/2}$</td>
</tr>
<tr>
<td>Particle velocity</td>
<td>$\mu^{1/2}$</td>
<td>$\mu^{1/2}$</td>
</tr>
<tr>
<td>Mass transport longshore velocity</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Friction coefficient $f$</td>
<td>$\Omega^{1/2}$</td>
<td>$\Omega$ (for surf zone)</td>
</tr>
<tr>
<td>Chezy coefficient $C_C$</td>
<td>$(\mu \Omega)^{1/2}$</td>
<td>$(\mu \Omega)^{1/2}$ (for surf zone)</td>
</tr>
<tr>
<td>Viscous sublayer $u_v$</td>
<td>$(\mu \Omega)^{1/2}$</td>
<td>$(\mu \Omega)^{1/2}$ (for surf zone)</td>
</tr>
<tr>
<td>Energy slope</td>
<td>$\mu$</td>
<td>$\mu$</td>
</tr>
<tr>
<td>Head loss</td>
<td>$\mu$</td>
<td>$\mu$</td>
</tr>
<tr>
<td>C) Sediment Characteristics</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Sediment size $D$</td>
<td>$\lambda^{3/2}$</td>
<td>$\lambda^{3/2}$</td>
</tr>
<tr>
<td>Apparent specific weight $\gamma'$</td>
<td>$\lambda^{3/2} \mu^{3/2}$</td>
<td>$\lambda^{3/2} \mu^{3/2}$ (for surf zone)</td>
</tr>
<tr>
<td>Size distribution $\sigma_D$</td>
<td>$1$</td>
<td>$1$</td>
</tr>
<tr>
<td>D) Initiation of Motion</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Critical boundary layer Reynolds number $R_C$</td>
<td>$R_C &gt; 500$</td>
<td>$1$</td>
</tr>
<tr>
<td>Critical boundary layer Froude number $F_{\phi_C}$</td>
<td>$1$</td>
<td>$1$</td>
</tr>
<tr>
<td>E) Sediment Transport Characteristics</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Boundary layer Reynolds number $R_\lambda$</td>
<td>$&gt; 500$</td>
<td>$1$</td>
</tr>
<tr>
<td>Boundary layer Froude number $F_\phi$</td>
<td>$1$</td>
<td>$1$</td>
</tr>
<tr>
<td>Volume of deposition or erosion</td>
<td>$\mu^{3/2}$</td>
<td>$\mu^{3/2}$</td>
</tr>
<tr>
<td>Time of bed evolution</td>
<td>$\lambda^{5/2} \mu^{-2}$</td>
<td>$\lambda^{5/2} \mu^{-2}$</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
Comparison of Various Approaches for Determination of Basic Scale Ratios of A Coastal Movable Bed Model

<table>
<thead>
<tr>
<th>Authors</th>
<th>Basic Relations</th>
<th>Method of Derivation</th>
</tr>
</thead>
</table>
| Goddet & Jaffry  | $n_D = \mu^{17/20} \omega^{8/5}$  
                 | $n_y = \mu^{3/20} \omega^{-3/5}$                         | Sediment motion due to combined action of waves and currents |
| (1960)           |                 |                                                           |
| Valenbois        | $\Omega = n_y^{-1}$  
                 | $n_y \sqrt[n_D]{1} = 1$                                    | Kinematics of motion of suspended sediments                 |
| (1960)           | $\mu = n_y \sqrt[n_D]{(n_H/\mu)^{-4}}$                  | Similitude of $D$                                          |
| Yalin (1963)     | $n_D = \mu^{3/4} \lambda^{1/2}$  
                 | $n_y \sqrt[n_D]{1} = 1$                                    | Similitude of $F$,                                        |
|                   |                 |                                                           |
| Bijker (1967)    | $n_y \sqrt[n_D]{1} = 1$                                 | Similitude of sediment transport characteristics, $F$, $R$, |
|                   | $\Omega \leftrightarrow$ equilibrium beach profiles    |                                                           |
| Present Method (1970) | $n_y \sqrt[n_D]{1} = 1$                               |                                                           |
|                   | $n_y = \mu^{3/2} \lambda^{-1/2}$ or $n_D = \lambda^{1/2} \mu^{-1}$ |                                                           |
|                   | $\Omega \leftrightarrow$ equilibrium beach profiles    |                                                           |
### LIST OF SYMBOLS

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>$C_c$</td>
<td>Chezy coefficient $(L^{2/3}T^{-1})^4$</td>
</tr>
<tr>
<td>$d$</td>
<td>depth of water</td>
</tr>
<tr>
<td>$d_b$</td>
<td>depth of water at breaking</td>
</tr>
<tr>
<td>$D$</td>
<td>mean sediment size</td>
</tr>
<tr>
<td>$D_s$</td>
<td>dimensionless sediment size $= \left( \frac{(\gamma_s - \gamma_f) g}{\sqrt{2\gamma_f}} \right)^{1/3}$, $D = (R_s/F_s)^{2/3}$</td>
</tr>
<tr>
<td>$E$</td>
<td>wave energy flux per unit length of the crest $(MLT^{-2})$</td>
</tr>
<tr>
<td>$f$</td>
<td>Darcy-Weisbach friction factor</td>
</tr>
<tr>
<td>$F_{s*}$</td>
<td>boundary layer densimetric Froude number $= u_*/\sqrt{\gamma g D}$</td>
</tr>
<tr>
<td>$F_{sC}$</td>
<td>critical boundary layer Froude number on initiation of sediment motion</td>
</tr>
<tr>
<td>$g$</td>
<td>acceleration of gravity</td>
</tr>
<tr>
<td>$H$</td>
<td>wave height</td>
</tr>
<tr>
<td>$k$</td>
<td>wave number $= 2\pi/L$</td>
</tr>
<tr>
<td>$L$</td>
<td>wave length</td>
</tr>
<tr>
<td>$n$</td>
<td>scale ratio with subscripts denoting corresponding quantities $= (value\ of\ model)/(value\ of\ prototype)$ e.g., $n_L$ is the scale ratio of the wave lengths</td>
</tr>
<tr>
<td>$q_s$</td>
<td>volumetric sediment transport rate per unit width $(L^2T^{-1})$</td>
</tr>
<tr>
<td>$Q_s$</td>
<td>volumetric sediment transport rate $(L^3T^{-1})$</td>
</tr>
<tr>
<td>$r$</td>
<td>radial coordinate</td>
</tr>
<tr>
<td>$R_h$</td>
<td>hydraulic radius</td>
</tr>
<tr>
<td>$R_b$</td>
<td>boundary layer Reynolds number $= U_b \delta / \nu$</td>
</tr>
<tr>
<td>$R_{s*}$</td>
<td>boundary layer Reynolds number based upon sediment size $= u_s D / \nu$</td>
</tr>
<tr>
<td>$R_{sC}$</td>
<td>critical boundary layer Reynolds number on initiation of sediment motion</td>
</tr>
<tr>
<td>$S$</td>
<td>slope</td>
</tr>
<tr>
<td>$S_e$</td>
<td>energy gradient</td>
</tr>
<tr>
<td>$t$</td>
<td>time</td>
</tr>
<tr>
<td>$t_b$</td>
<td>time of bed evolution</td>
</tr>
<tr>
<td>$T$</td>
<td>wave period</td>
</tr>
<tr>
<td>$u$</td>
<td>horizontal velocity</td>
</tr>
<tr>
<td>$u_C$</td>
<td>critical velocity for sediment motion</td>
</tr>
</tbody>
</table>
\( u_c \)    \[ \text{shear velocity} = \sqrt{\frac{\tau}{\rho}} \]

\( u_A \)    \[ \text{current shear velocity} \]

\( u_w \)    \[ \text{wave shear velocity} \]

\( U_w \)    \[ \text{horizontal velocity} \]

\( U_0 \)    \[ \text{velocity immediately above the boundary layer} \]

\( v \)    \[ \text{vertical velocity} \]

\( w \)    \[ \text{sediment fall velocity} \]

\( x \)    \[ \text{horizontal coordinate} \]

\( y \)    \[ \text{vertical coordinate} \]

\( \delta \)    \[ \text{boundary layer thickness} \]

\( \delta_L \)    \[ \text{laminar boundary layer thickness parameter} \]

\( \delta_T \)    \[ \text{turbulent boundary layer thickness} \]

\( \gamma_f \)    \[ \text{specific weight of the fluid} \]

\( \gamma_s \)    \[ \text{specific weight of the sediment} \]

\( \gamma' \)    \[ \text{apparent specific weight of the sediment} = (\gamma_s - \gamma_f)/\gamma_f \]

\( \lambda \)    \[ \text{horizontal scale} \]

\( \mu \)    \[ \text{vertical scale, dynamic viscosity of the fluid} (\text{ML}^{2}\text{T}^{-1}) \]

\( \nu \)    \[ \text{kinematic viscosity of the fluid} \]

\( \Omega \)    \[ \text{distortion} = \mu/\lambda \]

\( \theta \)    \[ \text{angle of wave incidence w r t the current direction} \]

\( \pi \)    \[ 3.1416 \]

\( \rho \)    \[ \text{mass density of the fluid} \]

\( \sigma_D \)    \[ \text{geometric standard deviation of the sediment size distributions} \]

\( \tau \)    \[ \text{shear stress} \]

\( \tau_c \)    \[ \text{critical shear stress on the initiation of sediment motion} \]
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